

Motor Protection SIPROTEC 7SK81

Protection
SIPROTEC Compact

Product description	Variants	Order No.
Motor protection device for connection to low-power transformers		1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 7 S K 8 1 □ 3 - □ E □ □ □ □ - 3 H □ 0 Short code □ □ □
Housing, binary inputs and outputs		
Housing 1/6 19", 4 x I, 3 BI, 5 BO ¹⁾ , 1 Life contact	1	
Housing 1/6 19", 4 x I, 7 BI, 8 BO ¹⁾ , 1 Life contact	2	
Housing 1/6 19", 4 x I, 3 x V, 3 BI, 5 BO ¹⁾ , 1 Life contact	3	
Housing 1/6 19", 4 x I, 3 x V, 7 BI, 8 BO ¹⁾ , 1 Life contact	4	
Housing 1/6 19", 4 x I, 3 BI, 5 BO ¹⁾ , 1 Life contact	5	
5 RTD inputs	6	
Housing 1/6 19", 4 x I, 3xV, 3 BI, 5 BO ¹⁾ , 1 Life contact	3	
5 RTD inputs		
Measuring inputs		
Low Power Input	3	
Rated auxiliary voltage		
DC 24 V to 48 V	1	
DC 60 V to 250 V; AC 115 V; AC 230 V	5	
Region-specific default- and language settings		
Region DE, IEC, language German ²⁾ , standard front	A	
Region World, IEC/ANSI, language English ²⁾ , standard front	B	
Port B (at bottom of device)		
No port	0	
IEC 60870-5-103 or DIGSI 4/modem, electrical RS232	1	
IEC 60870-5-103, DIGSI 4/modem or RTD-box, electrical RS485	2	
IEC 60870-5-103, DIGSI 4/modem or RTD-box, optical 820 nm, ST-connector	3	
Further protocols see supplement L	9	L 0 □
PROFIBUS DP slave, electrical RS485		A
PROFIBUS DP slave, optical, double ring, ST-connector		B
Modbus, electrical RS485		D
Modbus, optical 820 nm, ST-connector		E
DNP3, electrical RS485		G
DNP3, optical 820 nm, ST-connector		H
IEC 60870-5-103, redundant, electrical RS485, RJ45-connector		P
IEC 61850, 100 Mbit Ethernet, electrical, double, RJ45-connector		R
IEC 61850, 100 Mbit Ethernet, optical, double, LC-connector		S
Port A (at bottom of device)		
No port	0	
With Ethernet interface (DIGSI, RTD-box, not IEC 61850), RJ45-connector	6	
Measuring / fault recording		
With fault recording, average values, min/max values	3	

(continued on next page)

1) 2 changeover/Form C.

2) Language selectable.

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	ANSI-No.	
Basic version (contained in all options)		
	50/51	Overcurrent protection phase $I >$, $I >>$, $I >>>$, I_p
	50N/51N	Overcurrent protection ground $I_E >$, $I_E >>$, $I_E >>>$, I_{EP}
	50N(s)/51N(s) ¹⁾	Sensitive ground fault protection $I_{EE} >$, $I_{EE} >>$, I_{EEP}
	49	Overload protection
	74TC	Trip circuit supervision
	50BF	Circuit breaker failure protection
	46	Negative sequence / unbalanced load protection
	86	Lockout
	48	Starting time supervision
	37	Undercurrent monitoring
	66/86	Restart inhibit
	14	Locked rotor protection
	51M	Load jam protection
		Motor statistics
		Parameter changeover
		Monitoring functions
		Control of circuit-breaker
		Flexible protection functions (current parameters)
		Inrush restraint
Directional sensitive ground fault, voltage and frequency protection	67N	Directional overcurrent protection ground, $I_E >$, $I_E >>$, I_{EP}
■	67N(s) ¹⁾	Directional sensitive ground fault protection, $I_{EE} >$, $I_{EE} >>$, I_{EEP}
	59N	Displacement voltage
	27/59	Under/Overvoltage
	81 U/O	Under-/overfrequency, $f <$, $f >$
	47	Phase rotation
	32/55/81R	Flexible protection functions (current and voltage parameters)): Protective function for voltage, power, power factor, frequency change

■ Basic version included.

1) Depending on the connected low-power current transformer the function will be either sensitive (I_{Ns}) or non-sensitive (I_N).
2) Only with position 6 = 1, 2 or 5.
3) Only with position 6 = 3, 4 or 6.